

Matrices: Eigenvalues, Eigenvectors (1)

1) λ is an eigenvalue of \underline{A} iff $(A - \lambda I)$ is singular $\Rightarrow \det(A - \lambda I) = 0$.

2) \vec{p}_i is an eigenvector of A associated to λ_i iff $(A - \lambda_i I) \vec{p}_i = 0$

* $\det(A - \lambda I)$ is the characteristic polynomial.

Example $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

$$A - \lambda I = \begin{bmatrix} 1-\lambda & 1 & 0 \\ 0 & 2-\lambda & 0 \\ 0 & 0 & 3-\lambda \end{bmatrix}$$

$$|A - \lambda I| = (1-\lambda)(2-\lambda)(3-\lambda) \leftarrow -(3-\lambda) = 0$$

Another example

(2)

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

$$\Rightarrow |A - \lambda I| = \begin{vmatrix} 2-\lambda & 3 \\ 1 & 4-\lambda \end{vmatrix} = (2-\lambda)(4-\lambda) - 3$$

$$= \lambda^2 - 6\lambda + 5 = 0 \Rightarrow \lambda = \left. \begin{array}{l} \uparrow \\ \text{tr } A \end{array} \right\} \left. \begin{array}{l} \uparrow \\ |A| \end{array} \right\}$$

Eigenvectors

$$\lambda_1 = 1 \quad (A - \lambda_1 I) \mathbf{p}_1 = \begin{vmatrix} 2-\lambda_1 & 3 \\ 1 & 4-\lambda_1 \end{vmatrix} \mathbf{p}_1 =$$

$$= \begin{vmatrix} 1 & 3 \\ 1 & 3 \end{vmatrix} \mathbf{p}_1 = 0$$

$$= \begin{vmatrix} 1 & 3 \\ 1 & 3 \end{vmatrix} \begin{bmatrix} p_{11} \\ p_{12} \end{bmatrix} = 0$$

$$\Rightarrow \boxed{p_{11} + 3p_{12} = 0}$$

$$\Rightarrow \left. \begin{array}{l} p_{11} = -3 \\ p_{12} = 1 \end{array} \right\} \mathbf{p}_1 = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$$

(3)

A 2×2 matrix need not have 2 eigenvalues.

Example $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

$$|A - \lambda I| = \lambda^2 \Rightarrow \lambda = 0$$

Eigenvector = $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$

SIMILARITY

A, B (matrices) are similar ($A \sim B$)
 \Leftrightarrow exist a nonsingular $P \ni$
 $B = P^{-1}AP.$

Proposition: Let $A \sim B$. Then the families of eigenvalues are the same.

Proof: Since $A \sim B \Rightarrow B = P^{-1}AP$

for some P nonsingular
Then $(B - \lambda I) = P^{-1}(A - \lambda I)P$

$$\begin{aligned} \text{Then } |B - \lambda I| &= |P^{-1}(A - \lambda I)P| = |P^{-1}| |A - \lambda I| |P| \\ &= |A - \lambda I| \end{aligned}$$

QED

(9)

Proposition $A \sim B \Rightarrow y$ is an eigenvector of B belonging to λ iff Py is an eigenvector of A belonging to λ .

Proof. $B = P^{-1}AP \Rightarrow$

$$\Rightarrow By = P^{-1}APy \quad \text{But } By = \lambda y$$

$$\Rightarrow P^{-1}APy = \lambda y \Rightarrow \underbrace{APy}_{\substack{\uparrow \\ \text{definition} \\ \text{of eigenvector}}} = \lambda \underbrace{Py}_{\uparrow}$$

~~###~~

definition of eigenvector

QED

Similar matrices have the same family of eigenvalues and corresponding eigenvectors

Theorem: Let A be a matrix with complex coefficients. If $P^{-1}AP = \Lambda$ where $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n) \Rightarrow (\lambda_1, \dots, \lambda_n)$ is a family of eigenvalues of A .

Proof: use proposition above!

We say A is diagonalizable if
there exists $P \ni P^{-1}AP = \Lambda$
(Λ diagonal)

(5)

Repeated ~~the~~ roots of $|A - \lambda I| = 0$
let $|A - \lambda I| = (\lambda_1 - \lambda)^{\alpha_1} \dots (\lambda_m - \lambda)^{\alpha_m} = 0$
 $\Rightarrow \alpha_i$ is the algebraic multiplicity
of λ_i .

In addition, let $\delta_i(\lambda_i)$ be the
number of eigenvectors of A correspon-
ding to λ_i .

We call $\delta_i(\lambda_i)$ the geometric
multiplicity of λ_i .

Lemma: let $\lambda_1, \dots, \lambda_s$ be distinct
eigenvalues of a matrix A ; let $x^i, i=1, \dots, s$
be the eigenvectors corresponding to λ_i
 $\Rightarrow (x^1, \dots, x^s)$ are linearly independent

Proof. Induction.

1) True for $s=1$ ($x^1 \neq 0$)

2) We need to prove that if
true for $s \geq 2$, then it is true
for $s = s+1$

True for s , ~~then~~ $0 = \alpha_1 x^1 + \dots + \alpha_s x^s + \dots + \alpha_{s-1} x^{s-1} \quad (6)$
 $\Rightarrow \alpha_1 = \alpha_2 = \dots = \alpha_{s-1} = 0$

Now, let

$$\alpha_1 x^1 + \dots + \alpha_s x^s = 0 \quad (*)$$

we will prove $\alpha_1 = \alpha_2 = \dots = \alpha_s = 0$

$$\alpha_1 x^1 + \dots + \alpha_s x^s = 0 \Rightarrow$$

$$\Rightarrow A(\alpha_1 x^1 + \dots + \alpha_s x^s) =$$

$$= \alpha_1 \lambda_1 x^1 + \dots + \alpha_s \lambda_s x^s = 0$$

Multiply $(\alpha_1 x^1 + \dots + \alpha_s x^s) = 0$ by λ_s and subtract from \dots

$$\Rightarrow \alpha_1 (\lambda_1 - \lambda_s) x^1 + \dots + \alpha_{s-1} (\lambda_{s-1} - \lambda_s) x^{s-1} = 0$$

However these are $0 \Rightarrow$

$$\alpha_i (\lambda_i - \lambda_s) = 0, \text{ but } \lambda_i \neq \lambda_s \Rightarrow \alpha_i = 0$$

$\forall i = 1, \dots, (s-1)$, which reduces $(*)$ to

$$\alpha_s x^s = 0 \Rightarrow \alpha_s = 0. \quad \square \text{ Q.E.D.}$$

(7)

Theorem: Let $\lambda_1, \dots, \lambda_s$ distinct eigenvalues of A , and let $x^{i1}, \dots, x^{i\delta_i}$ the eigenvectors of λ_i

$\Rightarrow (x^{11}, \dots, x^{1\delta_1}, \dots, x^{s1}, \dots, x^{s\delta_s})$ are b_i .

Proof:

Suppose $\sum_{i=1}^s \sum_{j=1}^{\delta_i} \alpha_{ij} x^j = 0$

Need to prove $\alpha_{ij} = 0 \quad \forall i, j$.

Let $x^i = \sum_{j=1}^{\delta_i} \alpha_{ij} x^j$. Now, x^i is an eigenvector belonging to λ_i or $x^i = 0$.

Suppose $x^i \neq 0$ for some $i = 1, \dots, s$.

$\Rightarrow \sum_{i=1}^s x^i = 0$, which is impossible

by the previous theorem. $\Rightarrow x^i = 0 \quad \forall i$

$\Rightarrow \alpha_{ij} = 0$

Q.E.D

(8)

Theorem A is diagonalizable iff

$$\alpha_i = \delta_i$$

Proof: (a loosely speaking one).

a) Let $\alpha_i = \delta_i \Rightarrow n = \sum \alpha_i = \sum \delta_i$

but $(x^{i_1}, \dots, x^{i_{\alpha_i}})$ are li.

$$\Rightarrow (x^{i_1}, \dots, x^{i_{\alpha_i}}, \dots, x^{i_1}, \dots, x^{i_{\alpha_m}})$$

are li. (previous theorem). \Rightarrow The matrix $P = [x^{i_1} \dots x^{i_{\alpha_m}}]$ will render the desired result.

b) A is diagonalizable. $\Rightarrow P$ exists.

\Rightarrow There are n vectors qualified to be eigenvectors.

JORDAN FORMS

(9)

Define $U_r = [u_{ij}] \Rightarrow u_{i, i+1} = 1$
 $u_{ij} = 0$ otherwise

$$U_3 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$U_4 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

etc.

first superdiagonals

Jordan Block: A matrix of the form $\lambda I_r + U_r$

Definition: a direct sum of two matrices is

$$A \oplus B = \begin{bmatrix} A & 0 \\ 0 & B \end{bmatrix}$$

Definition A matrix is in a Jordan canonical form if it is a direct sum of Jordan blocks

$$A = (\lambda_1 I_{r_1} + U_{r_1}) \oplus \dots \oplus (\lambda_k I_{r_k} + U_{r_k})$$

Example

$$\Lambda = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix} = (0I_2 + U_2) \oplus (2I_1 + U_1)$$

Theorem: let A be a matrix. A matrix Λ in Jordan canonical form exists such that $\Lambda \sim A$.



We have some candidates for columns of P . They are the eigenvectors. What happens when Λ is a Jordan form. Need to find other columns of P .

$$P = \begin{bmatrix} p_1 & \dots & p_2 & \dots \\ \vdots & & \vdots & \end{bmatrix}$$

misses

know A ,
know Λ

$s = \#$ of \neq eigenvalues

$\Rightarrow n-s$ vectors to be determined.

$\Rightarrow (n-s) \times n$ unknowns

but $A = P^{-1} \Lambda P$

$PA = \Lambda P \Rightarrow \underline{\underline{n^2 \text{ equations}}}$

Functions of Matrices

(11)

Let $f(\lambda) = \sum c_i \lambda^i$

we define $f(A) = \sum c_i A^i$

$$A^0 \triangleq I$$

Suppose $B = P^{-1} A P$

$$\Rightarrow B^2 = (P^{-1} A P)(P^{-1} A P) = P^{-1} A^2 P$$

$$\Rightarrow B^k = P^{-1} A^k P$$

What do I use here?

$$\begin{aligned} \Rightarrow f(B) &= \sum c_i (P^{-1} A P)^i = \\ &= \sum c_i P^{-1} A^i P = P^{-1} \sum c_i A^i P \\ &= P^{-1} f(A) P \end{aligned}$$

Hamilton Cayley Theorem

it also works if f is an ∞ series

Every matrix satisfies its own characteristic equation.

Proof: We will prove it for A diagonalizable only.

$$\text{Let } |A - \lambda I| = p(\lambda) = (\lambda - \lambda_1)(\lambda - \lambda_2) \dots (\lambda - \lambda_n)$$

$$\Rightarrow A = P^{-1} \Lambda P \Rightarrow p(A) = P^{-1} p(\Lambda) P$$

but

(12)

$$P(\Lambda) = (\Lambda - \lambda_1 I) (\Lambda - \lambda_2 I) \dots (\Lambda - \lambda_n I)$$

However

$$\begin{aligned} (\Lambda - \lambda_1 I) (\Lambda - \lambda_2 I) &= \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 & 0 & \\ 0 & 0 & 0 & \\ 0 & 0 & \lambda_3^2 & \\ \dots & \dots & \dots & \lambda_n^2 \end{bmatrix} \end{aligned}$$

In other words. $P(\Lambda) = 0$

$$\Rightarrow P(A) = 0$$

Q.E.D

It is also true for A non-diagonalizable.

Consequence :

let $f(\lambda)$ be any polynomial

$$f(\lambda) = g(\lambda) + h(\lambda)P(\lambda)$$

$$\Rightarrow f(A) = g(A) + h(A) \underbrace{P(A)}_{=0}$$

example

$$A = \begin{bmatrix} -1 & 1 & 1 \\ -3 & 3 & 1 \\ -4 & 3 & 2 \end{bmatrix}$$

$$p(\lambda) = (1-\lambda)^2 (2-\lambda)$$

$$\text{let } f(A) = (1-\lambda)^4 (2-\lambda)^3 + (\lambda+1)$$

$$\Rightarrow f(t) = (2-\lambda)p(\lambda)^2 + (\lambda+1) \quad (*)$$

$$\begin{aligned} \Rightarrow f(A) &= (I-A)^4 (2I-A)^3 + (A+I) = \\ &= g(A) = A+I \end{aligned}$$

$$A^z = ? \quad p(\lambda) = \lambda^n + a_1 \lambda^{n-1} + \dots + a_n \quad (13)$$

$$\Rightarrow \left[A^n = -a_1 A^{n-1} - a_2 A^{n-2} - \dots - a_n I \right]$$

↓ which can be used recursively

However, note that if λ_i is an eigenvalue of $A \Rightarrow \lambda_i^m$ is an eigenvalue of A^m

$$\Rightarrow p(\lambda^m) = \lambda^{mm} + a_1 \lambda^{m(n-1)} + \dots + a_n$$

$$\Rightarrow A^z = -a_1 A^{z-m} - a_2 A^{z-2m} - \dots - a_n I$$

(14)

Also,

$$I = -\frac{1}{a_n} [A^n + a_1 A^{n-1} + \dots + a_{n-1} A]$$

$$\Rightarrow A^{-1} = -\frac{1}{a_n} [A^{n-1} + a_1 A^{n-2} + \dots + a_{n-1} I]$$

Remarkable!

but very seldom used

Finally, we said $f(B) = P^{-1} f(A) P$
is valid for series -

$$\Rightarrow e^A = I + A + \frac{A^2}{2!} + \dots + \frac{A^n}{n!} + \dots$$

$$e^{At} = I + At + \frac{A^2 t^2}{2!} + \dots + \frac{A^n t^n}{n!} + \dots$$

Moreover

$$\frac{d}{dt} [e^{At}] = A e^{At}$$

Immediate consequence for (15)
systems of ODE's.

$$x' = Ax \quad \text{let } A = P^{-1} \Lambda P$$

$$\Rightarrow x' = P^{-1} \Lambda \underbrace{Px}_{=y} = P^{-1} \Lambda y$$

$$\Rightarrow y' = P x' \Rightarrow y' = \Lambda y \quad \begin{array}{c} \uparrow \\ \text{diagonal} \end{array}$$

$$\Rightarrow y_i' = \lambda_i y_i \Rightarrow y_i = c_i e^{\lambda_i t}$$

$$\Rightarrow y = e^{\Lambda t} c_1 \quad \text{but } y = Px$$

vector
of constants

$$\Rightarrow x = P^{-1} y = P^{-1} e^{\Lambda t} c_1$$

However, $e^{At} = P^{-1} e^{\Lambda t} P \Rightarrow$

$$P^{-1} e^{\Lambda t} = e^{At} P^{-1}$$

$$\Rightarrow \boxed{x = e^{At} P^{-1} c_1 = e^{At} c}$$

This
is what
we call
elegance!

(16)

Let us apply variation of parameters to solve $x' = Ax + g$

Assume ϕ is a fundamental matrix of the ODE system (A constant $\Rightarrow \phi = e^{At}$)

Let $\psi_p = \phi h$.

$$\psi_p' = A \phi h + g.$$

\Downarrow

$$\phi' h + \phi h' = A \phi h + g$$

$A \cancel{\phi h} + \phi h' = A \cancel{\phi h} + g \Rightarrow \phi h' = g$
 $h' = \phi^{-1} g$

$$\Rightarrow h = \int \phi^{-1}(s) g(s) ds$$

\Rightarrow general solution is

$$\tilde{\phi} = \phi \underline{c} + \phi \int_{t_0}^t \phi^{-1} g ds$$

\uparrow obtained from initial conditions

Conditions at two points

(17)

$$\begin{cases} \dot{x} = Ax + g \\ w_a x(a) + w_b x(b) = b \end{cases}$$

$$\text{Let } D = w_a \phi(a) + w_b \phi(b)$$

↑ fundamental matrix

but

$$\tilde{\phi} = \phi c + \underbrace{\phi \int_a^t \phi^{-1} g ds}_{\tilde{\psi}} = \phi c + \tilde{\psi}$$

$$\Rightarrow w_a \tilde{\phi}(a) + w_b \tilde{\phi}(b) = Dc + \tilde{e} = b$$

$$\text{where } \tilde{e} = w_a \tilde{\psi}(a) + w_b \tilde{\psi}(b) = 0$$

⇒ Need to solve

$$Dc = b - \tilde{e}$$

↑
D needs to be of full rank.

Symmetric Matrices

(18)

$$A^T = A$$

- 1) All eigenvalues are real
- 2) λ is of multiplicity $k \Rightarrow$ eigenspace is of dimension k
- 3) eigenvectors are orthogonal.

Proof

$$1) \quad Ae = \lambda e$$

$$A\bar{e} = \bar{\lambda}\bar{e}$$

$$\Rightarrow (Ae)^T \bar{e} = (\lambda e)^T \bar{e} = \lambda e^T \bar{e}$$

$$\Rightarrow (A\bar{e})^T e = (\bar{\lambda}\bar{e})^T e = \bar{\lambda} \bar{e}^T e$$

$$0 = (\lambda - \bar{\lambda}) e^T \bar{e}$$

$$\hookrightarrow \lambda = \bar{\lambda}$$

$$\Rightarrow \lambda \text{ is real}$$

2) Proven previously (they are li.)

$$3) \quad Ae_j = \lambda_j e_j \quad A e_k = \lambda_k e_k$$

$$\Downarrow$$

$$e_k^T A e_j = e_k^T \lambda_j e_j$$

$$\Downarrow$$

$$(A e_k)^T = \lambda_k e_k^T$$

$$\Downarrow$$

$$e_k^T A^T e_j = \lambda_k e_k^T e_j$$

$$\Rightarrow e_k^T A e_j = e_k^T \lambda_j e_j$$

$$e_k^T A^T e_j = e_k^T \lambda_k e_j$$

$$A = A^T \implies 0 = (\lambda_j - \lambda_k) e_k^T e_j \implies e_k^T e_j = 0 \quad \text{QED}$$

Hermitian Matrices

(19)

$$A^\# \equiv \bar{A}^T$$

↑
hermitian
conjugate of
A

If $\bar{A} = A \Rightarrow A$ is real

If $A^\# = A \Rightarrow A$ is hermitian

- 1) Hermitian matrices have real eigenvalues
- 2) " " " " orthogonal eigenvectors